

KEY BENEFITS

Uses the same controller as larger Yaskawa robots

Easy vision integration with MotoSight 2D, a Cognex In-Sight based vision system

Yields extraordinary production results, while requiring minimal capital investment

High work envelope to mounting surface ratio

Flexible asset; easily re-deployable as production needs change

SPECIFICATIONS

10 kg maximum payload 850 mm radial reach 420 mm U-axis stroke

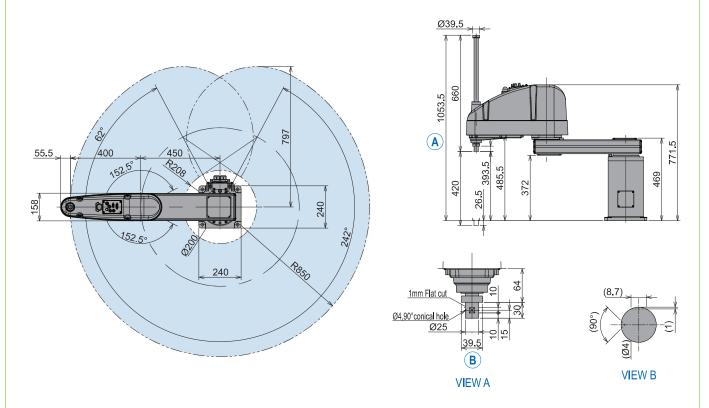
- CONTROLLERS

DXM100 FS100 MLX200

- 4-axis SCARA robot ideal for high-speed handling and assembly systems.
- Offers superior performance in applications such as assembly, dispensing, part kitting, small part handling, case packing, lab automation, packaging, solar and semiconductor processing.
- Ideal for multi-process systems requiring pick-and-place capability.
- Easily integrates with existing robot applications to expand current automated processes.
- Rounds out the Yaskawa product line of 4-15 axis robots with payloads of 1-800 kg.

- Uses same controller as other Yaskawa robots. Enclosure size may vary depending on robot size and payload.
- Offers high speed in a compact form that requires minimal mounting space.
- Features a radial reach of 850 mm, long (420 mm) U-axis stroke and 10 kg maximum payload.
- External axes available, further expanding the capabilities of this flexible asset.
- High repeatability with compliance in all axes make these robots ideal for assembly tasks.
- Wide variety of fieldbus connectivity available.

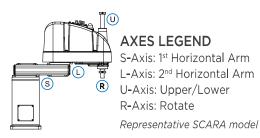
MYS850LF



All dimensions are metric (mm) and for reference only. Request detailed drawings for all design/engineering requirements.

SPECIFICATIONS						
Axes	Maximum motion range [°]	Maximum speed [°/sec.]	Allowable moment of inertia [kg•m²]	Repeatability [mm]	Controlled axes Payload [kg]	4 5 Rated/10 Max
S+L	850 mm	=	-	±0.025	Radial reach [mm]	850
S	+242/ - 62	424	-	-		
L	±152.5	678	-	-	U-axis stroke [mm]	420
U	420 mm	2,350 mm/s	-	±0.01	Weight [kg]	48
R	±360	2,415	0.02 Rated/0.25 Max	±0.005°	Power rating [kVA]	1.25

NOTE: Maximum speed and moment of inertia may vary depending on load.





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